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## بررسی اثر پارامتر حالت در معادلات رفتاری با استفاده از نتایج آزمایش های سانتریفوژ منوچهر لطیفی نمین<sup>\*۱</sup> و زهرا سبزی<sup>۲</sup>

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VELACS 50g Pastor & Zienkiewicz Mark III

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. Pastor & Zienkiewicz(1990)

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واژه های کلیدی:

مقدمه

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[] Been & Jefferies(1985)

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(*p*)

$$(\eta)$$
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$$(p')$$
$$\eta = M_g$$

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Ishihara.et.al (1975)

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$$(\theta) - M_g$$

$$[]$$

$$M_g = 6.Sin\varphi'_g /(3 - Sin\varphi'_g.Sin3\theta) \qquad ()$$

$$\varphi'_g$$

$$q = 6p'.Sin\varphi'_g /(3 - Sin\varphi'_g.Sin3\theta)$$
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 $d_{g} = d\varepsilon_{p}^{p} / d\varepsilon_{q}^{p} \approx d\varepsilon_{p} / d\varepsilon_{q}$  $d\varepsilon_{q}^{p} \quad d\varepsilon_{p}^{p}$ 

$$darepsilon_q$$

 $G = q - 6.Sin \varphi_g' \,/ (3 - Sin \varphi_g'.Sin 3\theta) \times$ ()  $(1 + 1/\alpha_g)(1 - (\,p'/\,p'_g\,))$ 

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( ) Pastor & Zienkiewicz Mark III مدل فرضيات اساسى

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 $d\varepsilon_p$ .

 $M_{f}$ 

 $\eta_{\max}$  [ ]  $\gamma_{DM}$ مدول پلاستیک بار گذاری $H_L = H_0.p'.(1 - \eta/\eta_f)^4.(H_v + H_s) imes$ 

ثابتهاي الاستيك

 $(H_{evop}, H_{esop})$ 

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 $M_g M_f$ 

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 $K = H_{evop}.p'$ 

 $G = H_{exop} \cdot p' / 3$ 

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$$H_{L} = H_{0} \cdot p' \cdot (1 - \eta / \eta_{f})^{4} \cdot (H_{v} + H_{s}) \times$$
()  
$$(\eta / \eta_{max})^{-\gamma_{DM}}$$
()  
$$\eta_{f} = (1 + 1 / \alpha_{f}) \cdot M_{f}$$
()  
$$H_{0}$$
$$H_{0}$$

$$(1-\eta/\eta_f)^4$$
 .

. 
$$\eta_f$$
  $H_v$ 

$$H_{v} = (1 - \eta / M_{g}) \qquad ()$$

$$H_{v} \qquad M_{g} \qquad \eta$$

$$H_{v}$$

Wilde (1977)  $H_s$ 

$$H_{s} = \beta_{0}.\beta_{1}.\exp(-\beta_{0}\xi) \qquad ()$$

$$\xi = \int \left| d\varepsilon_{q} \right| \qquad ()$$

$$d\varepsilon_{q} \cdot \beta_{1} \cdot \beta_{0}$$

 $M_{g}$  p'-q

$$H_s$$

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 $M_{g}$ 

استفاده از پارامتر حالت در مدل & Pastor Zienkiewicz Mark III



ارزیابی مدل اصلاح شده

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VELACS

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VELACS

تعریف مکانیزمی برای تعیین <sub>8</sub>

(CSL)  $M_{g}$ :

$$if \quad \psi \ge 0 \Rightarrow M_g = M_{cs} * (2 - \exp(-\psi))$$

$$()$$

$$if \quad \psi \prec 0 \Rightarrow M_g = M_{cs} * (\exp(\psi))$$

$$\psi$$
  $M_{cs}$ 

$$\psi = e - e_{cr} \tag{()}$$

$$e_{cr} = \Gamma - \lambda * \ln(p')$$
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شکل ۴: هندسه مدل شماره ۱۱ پروژه VELACS.

شکل ۲: محل قرار گیری ابزار دقیق در مدل شماره ۳.

جدول ۱: محل قرار گیری ابزار دقیق در مدل شماره ۳.

Transducer	Instrument ID	Coordinates (in)				
Accelerometer		x	у	Z		
	A1	-3/00	2/73	0/00		
	A2	-3/00	2/20	0/00		
	A3	-3/00	4/50	0/00		
	A4	3/50	3/00	6/96		
	A5	3/50	4/00	6/96		
	A6	10/50	3/00	6/96		
	A7	10/50	4/00	6/96		
Linear variable differential transducer	LVDT1	14/50	2/80	2/68		
	LVDT2	14/50	2/80	4/69		
	LVDT3	14/50	2/80	6/69		
	LVDT4	14/50	2/80	8/70		
	LVDT5	2/90	3/50	8/80		
	LVDT6	11/19	3/50	8/85		
Pore pressure transducer	P1	2/33	3/50	0/13		
	P2	11/67	3/50	0/13		
	P3	2/33	3/50	3/48		
	P4	5/25	3/50	3/48		
	P5	8/75	3/50	3/48		
	P6	11/67	3/50	3/48		



جدول ۲: پارامتر های مدل اصلی خاک %70, Nevada Sand Dr=40%.

	$M_{g}$	$M_{f}$	$\alpha_{g}$	$\alpha_{_f}$	$H_{evop}$	$H_{esop}$	$eta_0$	$\beta_1$	${H}_0$	$H_{u0}$	$\gamma_u$	$\gamma_{DM}$
Nevada Sand 40%	1/10	۱/۰۳۵	·/۴۵	۰/۴۵	v v · · · ·	1100	4/4	• / ٢	÷	۴۰۰۰۰۰	۲/۰	•/•
Nevada Sand 70%	1/88	١/٣٠	./40	•/40	۲	۲	4/1	• / ٢	۷۵۰	4	۲/۰	۴/۰

جدول ۳: پارامتر های مدل اصلاح شده خاک %70 , %Nevada Sand Dr=40.

	$M_{cs}$	Γ	λ
Nevada Sand 40%	1/15	2/5	0/2
Nevada Sand 70%	1/32	2/5	0/2

مدل شماره ۱۱.	دقیق در	گیری ابزار ا	قرار ٔ	۴: محل	جدول
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Transducer	Instrument ID	Coordinates (m)		
		х	У	Z
	ACC1	47/0	3/5	1/5
	ACC2	47/0	20/5	1/5
	ACC3	19/0	12/0	0/25
Assolutionstar	ACC4	24/0	12/0	1/4
Acceleronneter	ACC8	19/5	12/0	4/0
	ACC9	18/0	12/0	6/0
	ACC10	8/5	12/0	6/0
	ACC11	23/8	12/0	7/0
	ACC12	21/0	12/0	7/1
	PPT2	15/0	12/0	4/5
	PPT3	10/0	12/0	5/8
Pore	PPT4	21/0	12/0	2/0
Pressure	PPT5	21/0	12/0	4/0
Transducer	PPT6	21/0	12/0	6/0
	PPT7	27/0	12/0	1/4
	PPT8	40/0	12/0	1/4
Vertical Displacement	LVDT1	25/0	12/0	7/0









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1 - Fabric	2 - State
3 - Critical state	4 - Characteristic Line
5 - Deviatoric	6 - Steady State Line
7 - VELACS: VErification of Liquefaction A	Analysis using Centrifuge Studies
8 - Laminar Box	9 - Nevada Sand
10 - Rigid Box	